



This project has received funding from the European Union's Horizon2020 research and innovation programme under grant agreement N° 863819

FlexPlan

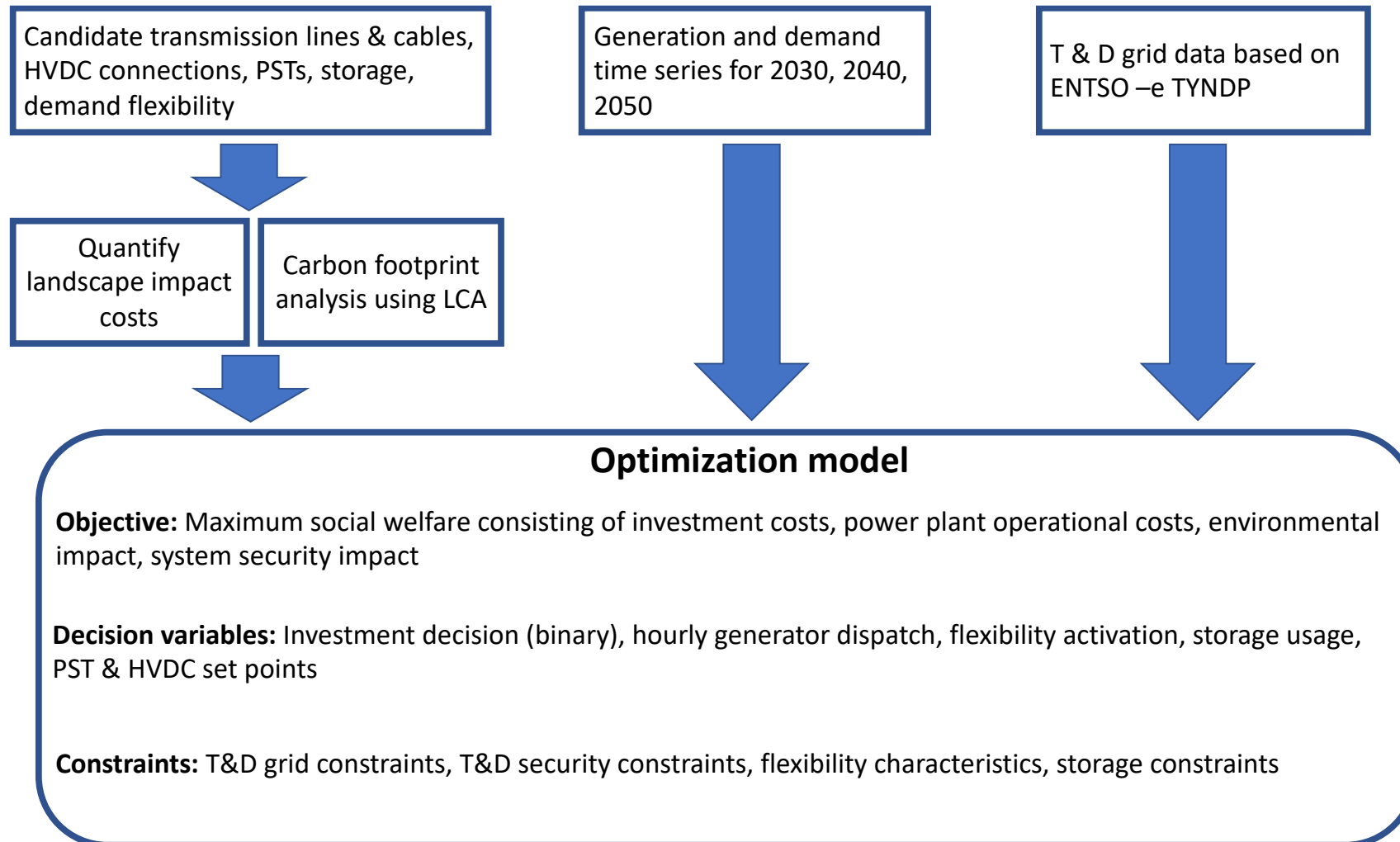
Decomposition methods for long-term network planning

24.11.2021

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Recapitulation of the FlexPlan approach



Optimization objective – General structure

- The maximum social welfare objective formulated as a cost minimization
 - Quantification of potential benefits not straight-forward without market assumptions
 - Danger of double counting benefits / costs due to complex flow of money
 - Eventually, all cost needs to be borne by consumers in some in way

- Objective function structure:

$$\min \sum_y \left[\sum_t \left[\sum_i (C_{y,t,i}) + \sum_{y,j} \alpha_{y,j} (C_{y,t,j}) \right] + \tilde{U}_{y,t,c} \Delta t \sum_c C_{u,t,y}^{voll} \Delta P_{u,c,t,y} \right] + \sum_j \alpha_{y,j} I_{y,j}$$

Operational
cost of
existing
equipment

Operational cost
of candidate
equipment

Expected cost due to
outages

CAPEX of
candidate
equipment

i... set of existing equipment

j... set of candidate equipment

α ... binary decision variable

t....set operational time points (8760h)

y... set of planning horizons (2030, 2040, 2050)

- Environmental impact cost considered as part of operational and CAPEX cost

Detailed formulation of the objective function

$$\min \sum_{y \in S_y} \left\{ \begin{aligned} & f_y^{d,o} \sum_{t \in S_t} \left[\sum_{g \in S_g} [C_{g,y}^{aq} + (\theta^{CO_2} G^{pf} + \theta^f) \eta_g^f] P_{g,t,y} + C_{g,y}^{res,curt} \Delta P_{g,t,y}^{res} + \right. \\ & \quad \sum_{j \in S_j} [C_{j,t,y}^{abs} P_{j,t,y}^{abs} + C_{j,t,y}^{inj} P_{j,t,y}^{inj}] + \sum_{j \in S_{jc}} [C_{jc,t,y}^{abs} P_{jc,t,y}^{abs} + C_{jc,t,y}^{inj} P_{j,t,y}^{inj}] + \\ & \quad \sum_{u \in S_u} [C_{u,t,y}^{nce} (P_{u,t,y}^{ref} - P_{u,t,y}^{nce}) + C_{u,t,y}^{ds} (\Delta P_{u,t,y}^{ds,up} + \Delta P_{u,t,y}^{ds,dn}) + C_{u,t,y}^{lc} \Delta P_{u,t,y}^{lc}] + \\ & \quad \left. \sum_{n \in S_n} (C_{n,t,y}^{EE} EE_{n,t,y} + C_{n,t,y}^{LL} LL_{n,t,y}) \right] + \\ & f_y^d \left[\sum_{j \in S_{jc}} \alpha_{jc,y} (I_{jc,y}^E (E_j^{max}) + I_{jc,y}^P (P_j^{max}) + FP_{jc,y}^{CO_2}) + \sum_{u \in S_u} \alpha_{u,y} (I_{u,y} + FP_{u,y}^{CO_2}) + \right. \\ & \quad \sum_{lc \in S_{lc}^{ac}} \alpha_{lc,y} (I_{lc,y} + FP_{lc,y}^{CO_2} + LS_{lc,y}) + \sum_{dc \in S_{lc}^{dc}} \alpha_{dc,y} (I_{dc,y} + FP_{dc,y}^{CO_2} + LS_{dc,y}) + \\ & \quad \left. \sum_{zc \in S_{zc}} \alpha_{zc,y} (I_{zc,y} + FP_{zc,y}^{CO_2} + LS_{zc,y}) + \sum_{bc \in S_{bc}} \alpha_{bc,y} (I_{bc,y} + FP_{bc,y}^{CO_2} + LS_{bc,y}) \right] \end{aligned} \right\} +$$

Air quality impact cost (points to $C_{g,y}^{aq}$)
Carbon footprint & landscape impact cost (points to $FP_{bc,y}^{CO_2}$)

Generator operational costs

Storage operational costs

Flexible demand operational costs

Grid security related costs

Capex storage + Capex demand flexibility

Capex AC and DC lines

Capex DC converters & PSTs

Model dimensions:

- Set of grid elements (x1000)
- Set of planning hours (8760)
- Set of planning years (2030 – 2040 - 2050)

Detailed formulation of the objective function

$$\min \sum_s \pi_s \left\{ \sum_{y \in S_y} f_y^{d,o} \left\{ \sum_{t \in S_t} \left[\sum_{g \in S_g} [C_{g,y}^{aq} + (\theta^{CO_2} G^{pf} + \theta^f) \eta_g^f] P_{g,t,y,s} + C_{g,y}^{res,curt} \Delta P_{g,t,y,s} + \right. \right. \right. \\ \left. \sum_{j \in S_j} [C_{j,t,y}^{abs} P_{j,t,y,s}^{abs} + C_{j,t,y}^{inj} P_{j,t,y,s}^{inj}] + \sum_{j \in S_{jc}} [C_{jc,t,y}^{abs} P_{jc,t,y,s}^{abs} + C_{jc,t,y}^{inj} P_{j,ct,y,s}^{inj}] + \right. \\ \left. \sum_{u \in S_u} [C_{u,t,y}^{nce} (P_{u,t,y,s}^{ref} - P_{u,t,y,s}^{nce}) + C_{u,t,y}^{ds} (\Delta P_{u,t,y,s}^{ds,up} + \Delta P_{u,t,y,s}^{ds,dn}) + C_{u,t,y}^{lc} \Delta P_{u,t,y,s}^{lc}] + \right. \\ \left. \sum_{n \in S_n} (C_{n,t,y}^{EE} EE_{n,t,y,s} + C_{n,t,y}^{LL} LL_{n,t,y,s}) \right] + \left. \sum_{j \in S_{jc}} \alpha_{jc,y} (I_{jc,y}^E (E_{jc}^{max}) + I_{jc,y}^P (P_{jc}^{max}) + FP_{jc,y}^{CO_2}) + \sum_{u \in S_u} \alpha_{u,y} (I_{u,y} + FP_{u,y}^{CO_2}) + \right. \\ f_y^d \left[\sum_{lc \in S_{lc}^{ac}} \alpha_{lc,y} (I_{lc,y} + FP_{lc,y}^{CO_2} + LS_{lc,y}) + \sum_{dc \in S_{lc}^{dc}} \alpha_{dc,y} (I_{dc,y} + FP_{dc,y}^{CO_2} + LS_{dc,y}) + \right. \\ \left. \sum_{zc \in S_{zc}} \alpha_{zc,y} (I_{zc,y} + FP_{zc,y}^{CO_2} + LS_{zc,y}) + \sum_{bc \in S_{bc}} \alpha_{bc,y} (I_{bc,y} + FP_{bc,y}^{CO_2} + LS_{bc,y}) \right] \right\} \right\}$$

Model dimensions:

- Set of grid elements (x1000)
- Set of planning hours (8760)
- Set of planning years (2030 – 2040 - 2050)
- Set of planning scenarios

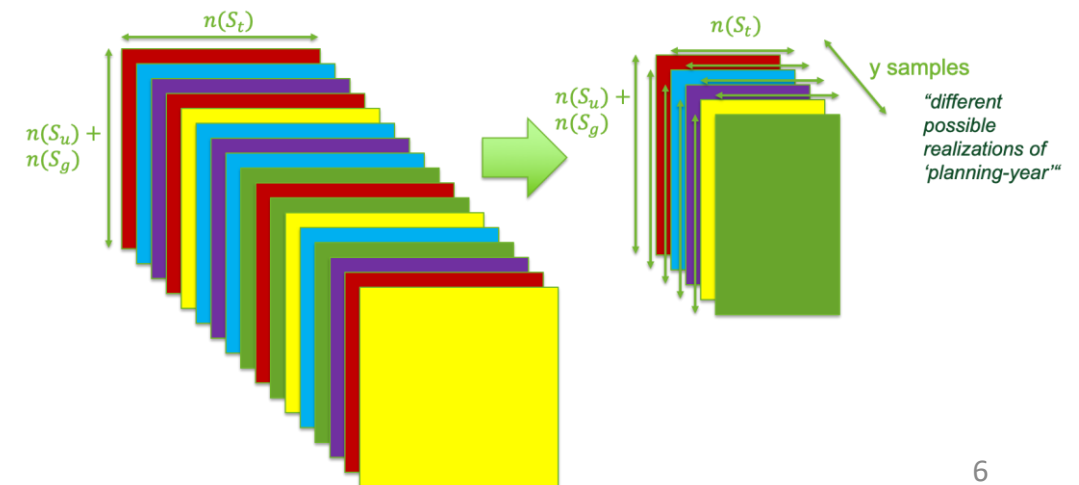
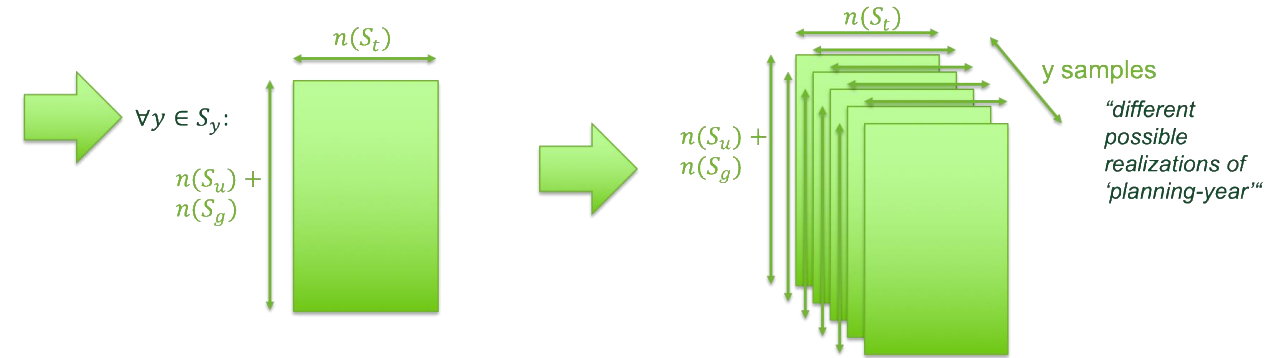
MILP problems will millions of decision variables and constraints



Model decompositions are needed!

Monte Carlo scenario generation and reduction to reduce problem size

- Generation of a high number of MC planning years from a limited set of scenarios with nodal resolution
- Reduction of the number of time series based on clustering techniques
- Reduction of the length of the time series (if required for computational reasons)

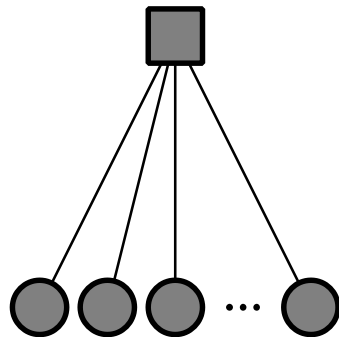


Benders decomposition

Solve smaller problems, but solve them multiple times

main problem

subproblems

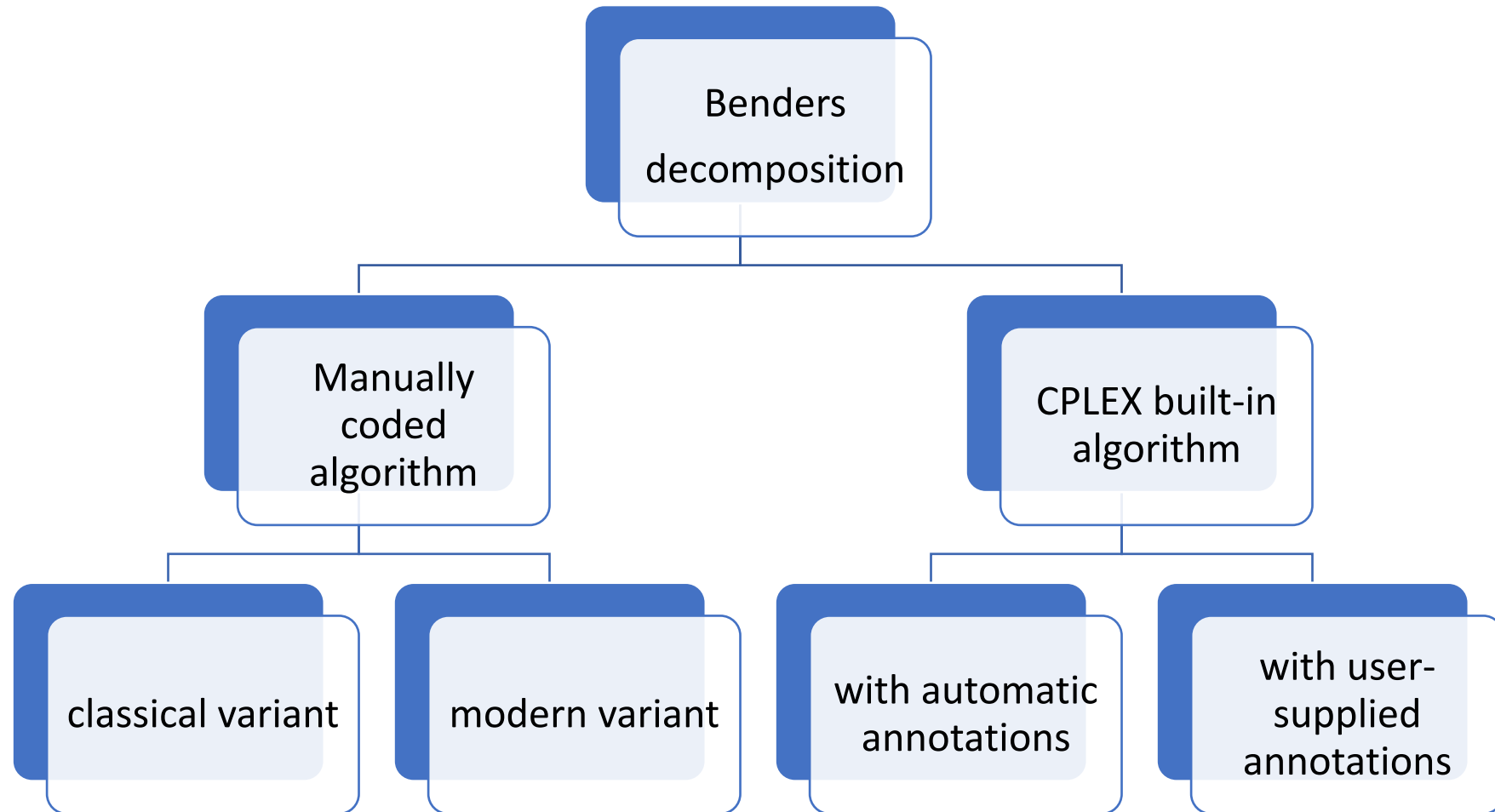


□ MILP

○ LP

- Main MILP problem:
 - optimizes **investments** (binary variables)
 - passes a set of **decisions** (whether to build network components) to subproblems
- 15 LP subproblems (3 years x 5 scenarios):
 - optimize **operations** (continuous variables)
 - provide a **surrogate** of the **operations cost** to the main problem
- The decomposition is exact (not an approximation)
- It can be stopped at any time, providing an approximate result

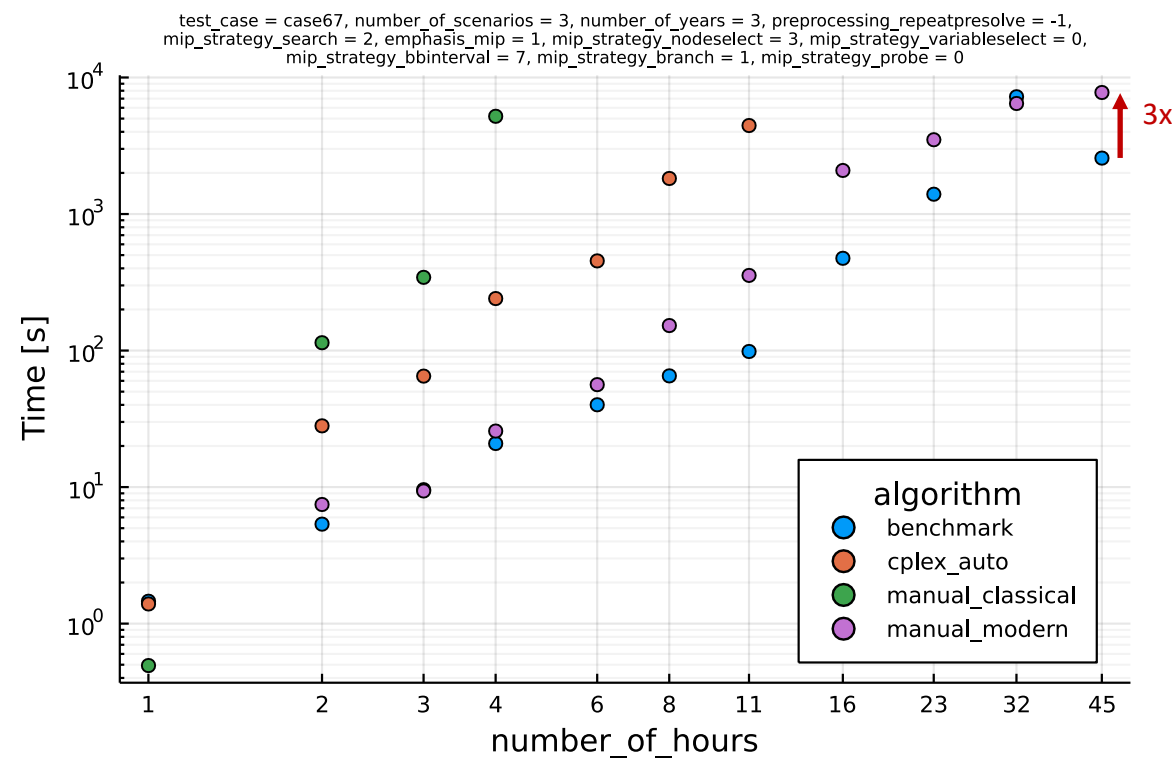
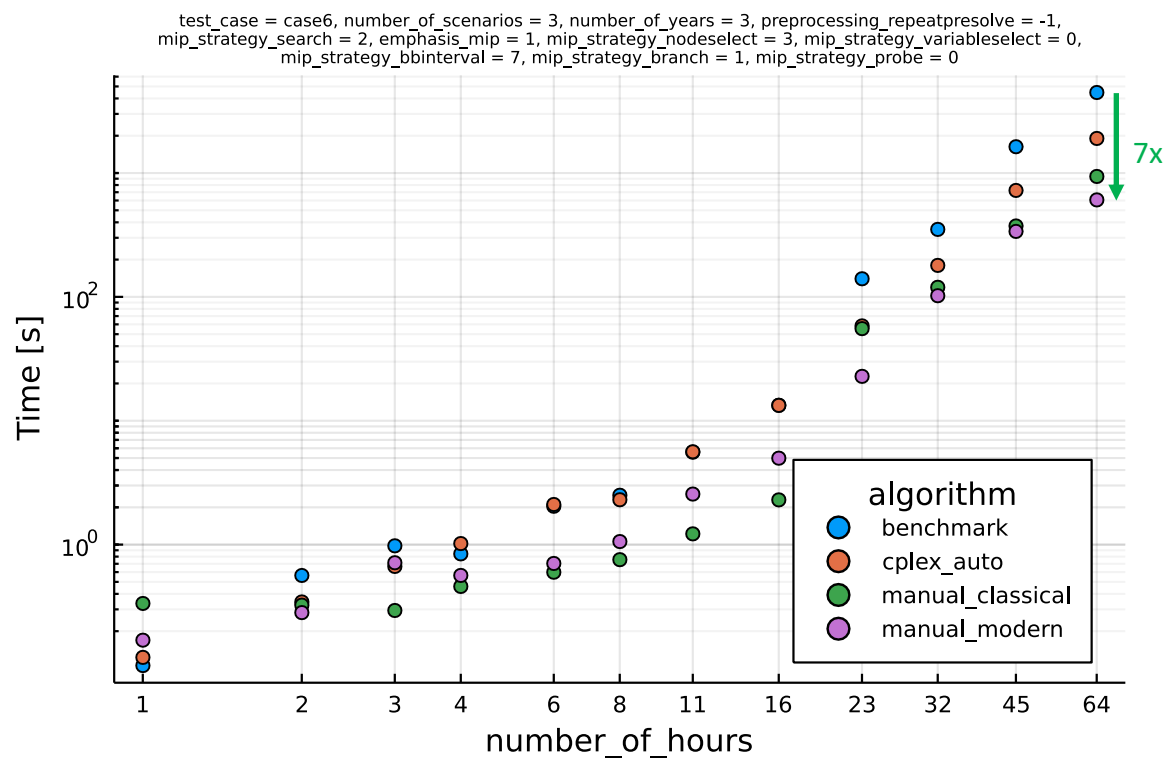
Implementation alternatives



Comparison of different implementations

The performance of the different variants is very case dependent

Performance of decompositions vs. single shot MILP problem (benchmark) on two different networks:



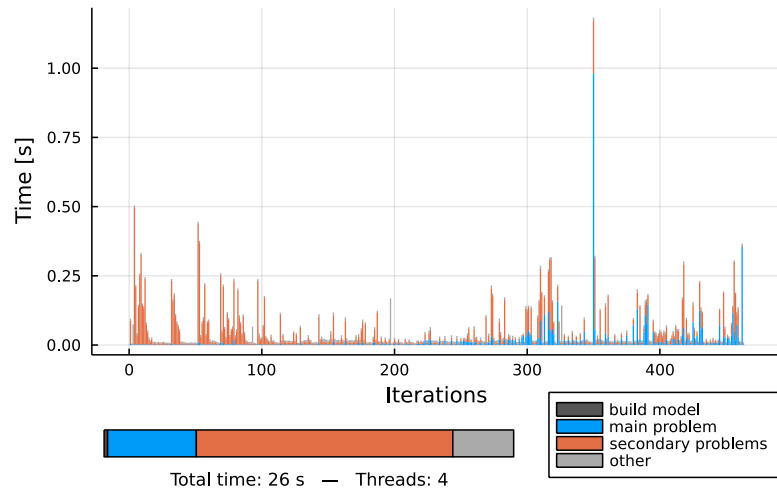
Performance of modern Benders decomposition

How is CPU time split between *main problem* and *subproblems*?

Comparison with different number of hours:

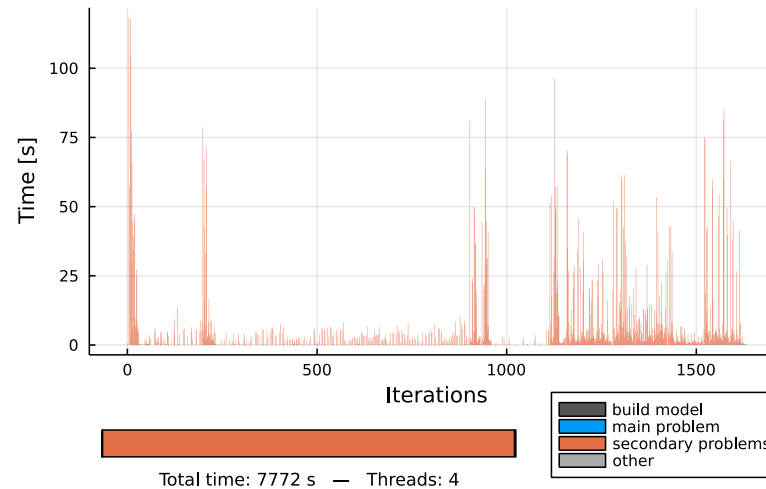
4 hours

Solve time



45 hours

Solve time



- As the size of the subproblems increases:
- Time per iteration grows more than linearly
- The number of iterations grows less than linearly
- Net effect: most of the time is spent on secondary problems

Takeaways

- The **time** of each iteration depends on secondary problem settings
⇒ Tune the secondary problem solver
- The **number** of iterations depends mostly on main problem setting
⇒ Tune the main problem solver

Preliminary conclusions

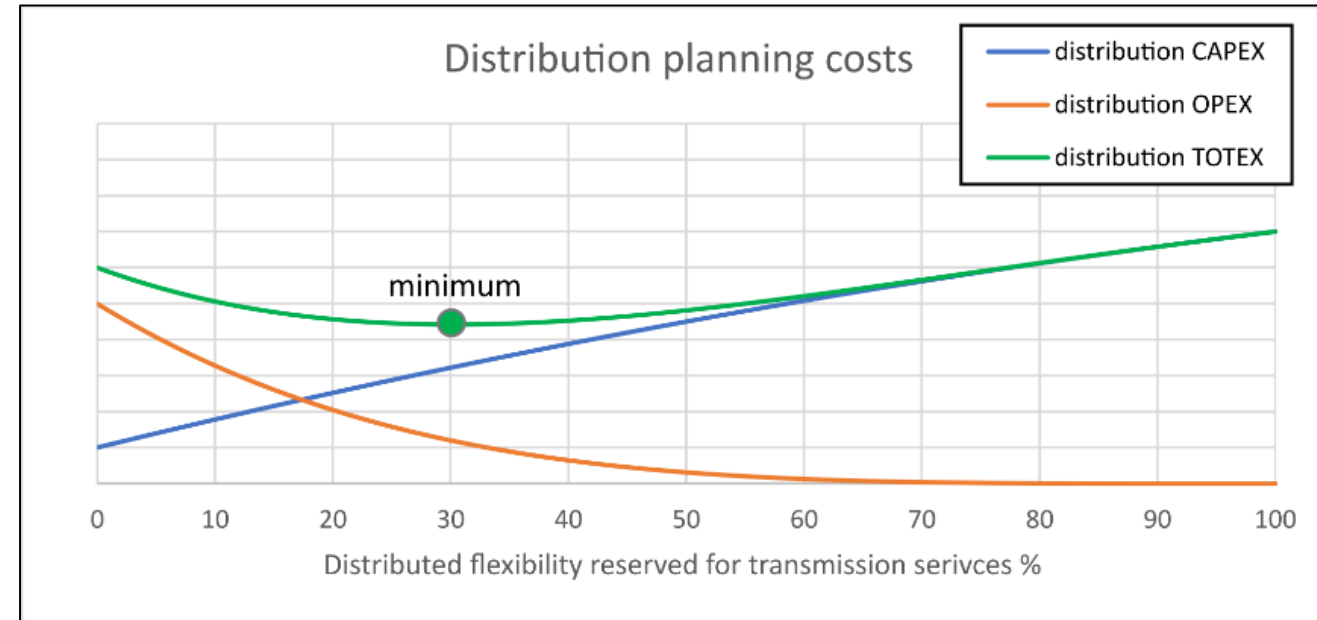
- Solver tuning is essential both for decomposed and single shot solutions
 - Challenge: finding suitable tuning parameters for different test cases
- The effect of an improved parallelization has to be investigated. It may have a beneficial effect to the simulation time.
 - Tests: 9 (3x3) subproblems on 4 cores \Rightarrow 3 passes
 - Final configuration: 15 (5x3) subproblems on 16 cores \Rightarrow 1 pass
- So far, all tests have been carried out on single machines with limited performance; performance on more powerful machines to be verified

Optimization of distribution network planning

(taking into account that local flexibility can be reserved for transmission services)

Literature and experience demonstrates that **exploiting local flexibility can reduce investments in reinforced lines and transformers**, potentially leading to lower planning costs.

For this reason, the EU directive 2019/944 states that (art.32.3) *the network development plan shall also include the use of demand response, energy efficiency, energy storage facilities or other resources that the distribution system operator is to use as an alternative to system expansion.*



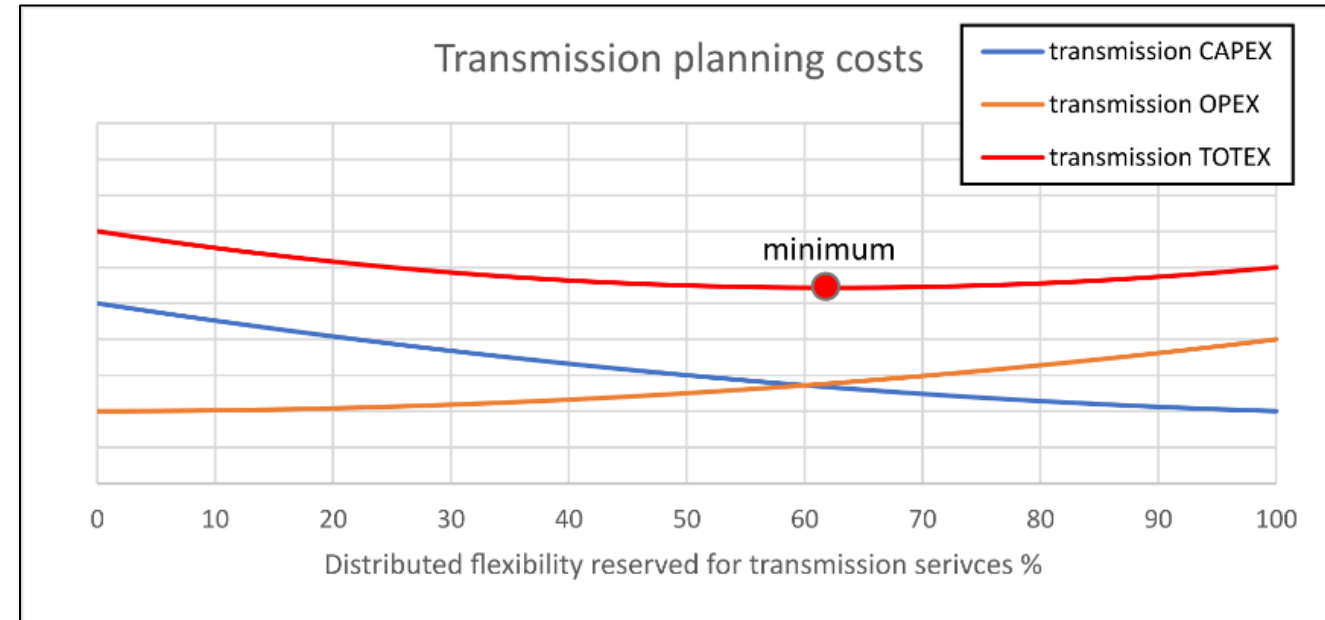
- CAPEX** capital expenditure
(mostly related to new/reinforced network asset)
- OPEX** operational expenditure
(mostly related to the operation of flexible resources)
- TOTEX** CAPEX+OPEX

Optimization of distribution network planning

(taking into account that local flexibility can be reserved for transmission services)

However, the resulting DSO-TSO share of distribution flexibility might be **non-optimal** from the transmission system perspective.

For this reason, the EU directive 2019/944 states that (art.40.5) *transmission system operators (shall) procure such services from providers of demand response or energy storage and shall promote the uptake of energy efficiency measures, where such services cost-effectively alleviate the need to upgrade or replace electricity capacity and support the efficient and secure operation of the transmission system*



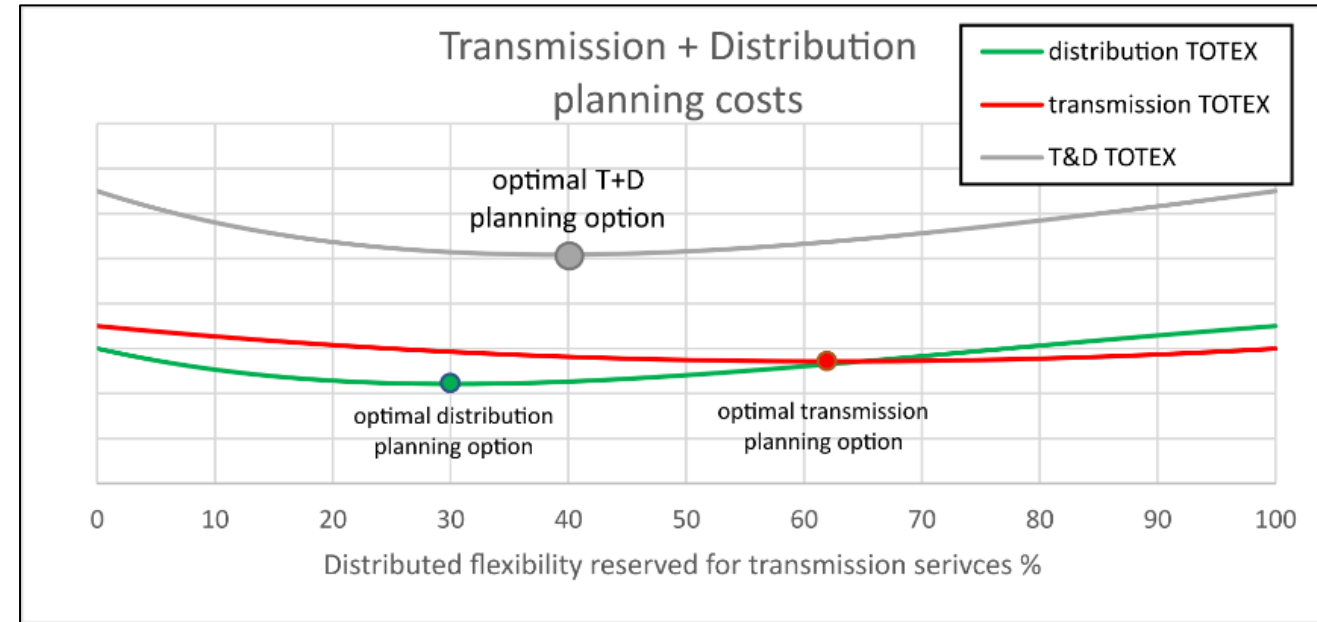
- CAPEX** capital expenditure
(mostly related to new/reinforced network asset)
- OPEX** operational expenditure
(mostly related to the operation of flexible resources)
- TOTEX** CAPEX+OPEX

Collaborative planning of transmission and distribution network

For this reason, **TSO and DSO should coordinate the exploitation of distribution flexibility**, which can be beneficial for the planning of both the networks and, eventually, the entire system.

Indeed, the EU directive 2019/944 states that

- *The distribution system operator shall consult all relevant system users and the relevant transmission system operators on the network development plan. (art.32.4)*



A **collaborative** (integrated) **planning of both transmission and distribution systems** allows the identification of the **global optimum**, which does not generally coincide with the ones resulting from a separated optimization limited to the perimeter of DSO and TSO respectively.

Planning of distribution network

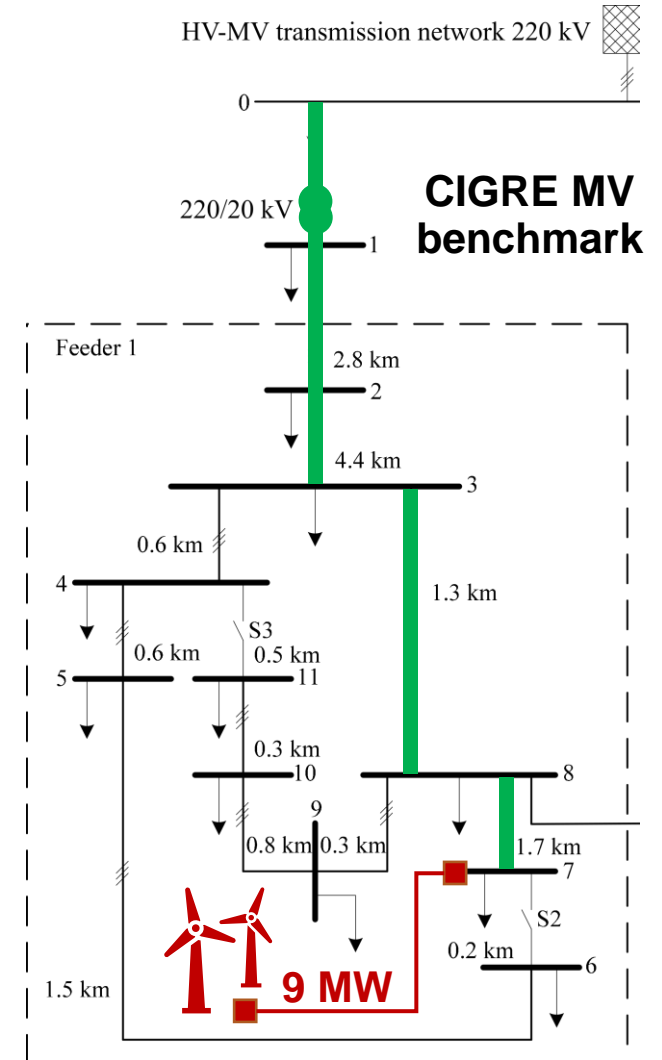
FlexPlan

Flexible demand/generation/storage can provide a multitude of services and distribution system operators could exploit them as **alternative planning option** with respect to conventional grid reinforcement.

min **CAPEX**

such that

- distribution grid constraints are respected



Planning of distribution network with flexibility

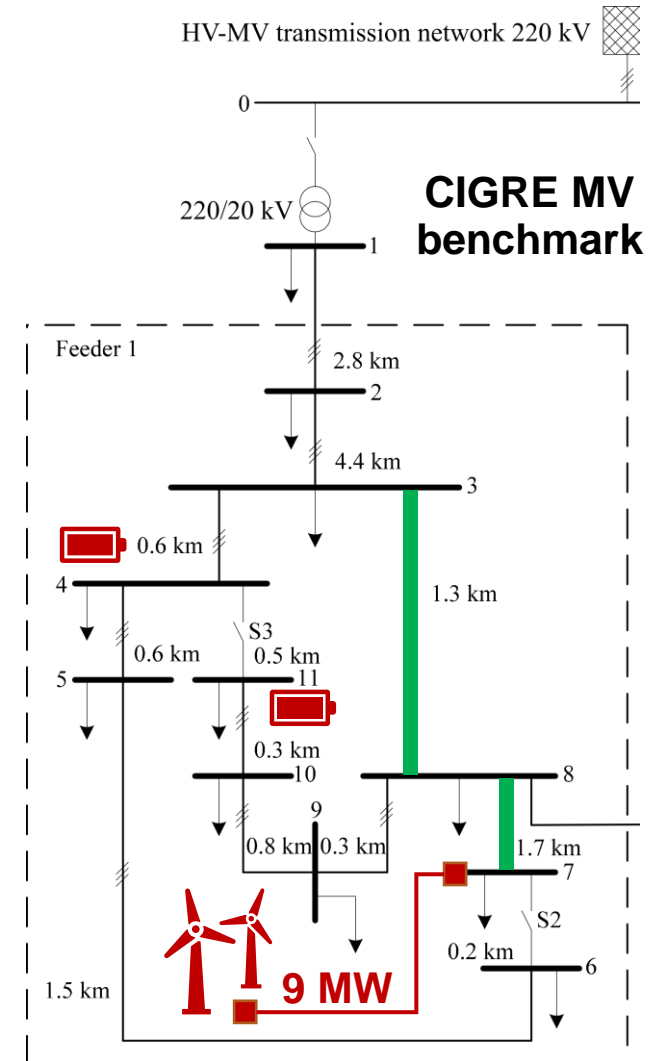
Flexible demand/generation/storage can provide a multitude of services and distribution system operators could exploit them as **alternative planning option** with respect to conventional grid reinforcement.

min **CAPEX**+**OPEX**

such that

- distribution grid constraints are respected

The engagement of existing/new flexible resources and the related **operational expenditure** can be competitive with respect to the reinforcement of grid sections.



Planning of transmission network with flexibility

FlexPlan

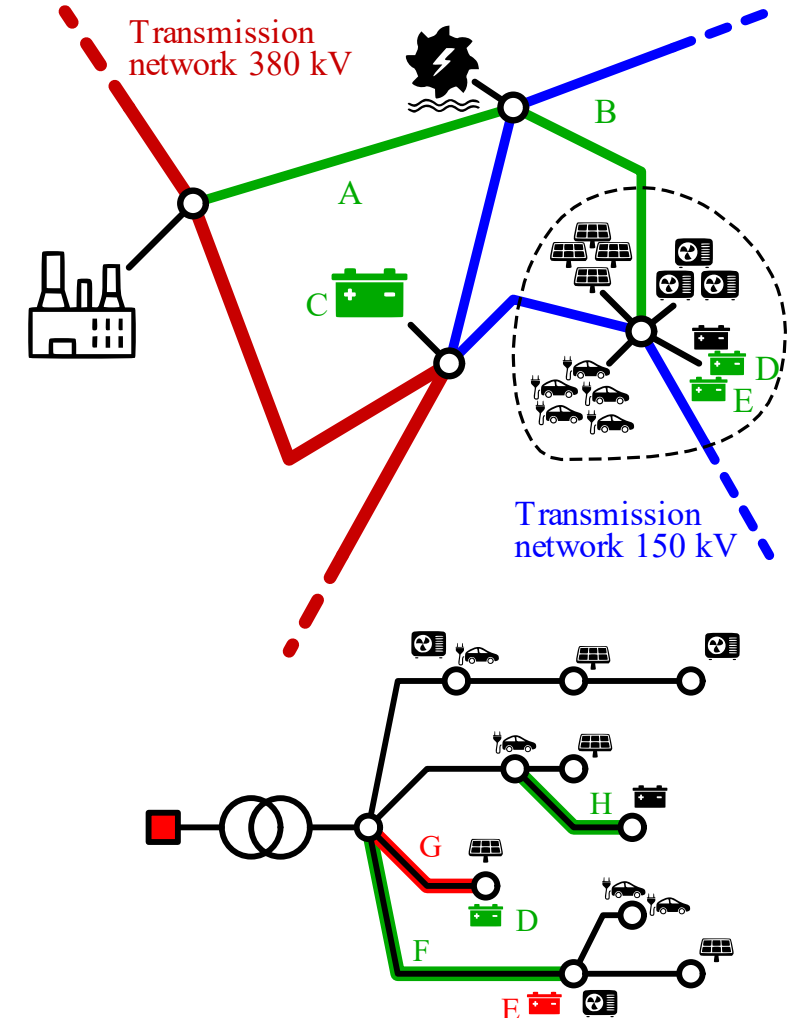
Flexible demand/generation/storage can provide a multitude of services and transmission system operators could exploit them as **alternative planning option** with respect to conventional grid reinforcement.

min **CAPEX+OPEX**

such that

- transmission grid constraints are respected
- distribution grid constraints are respected

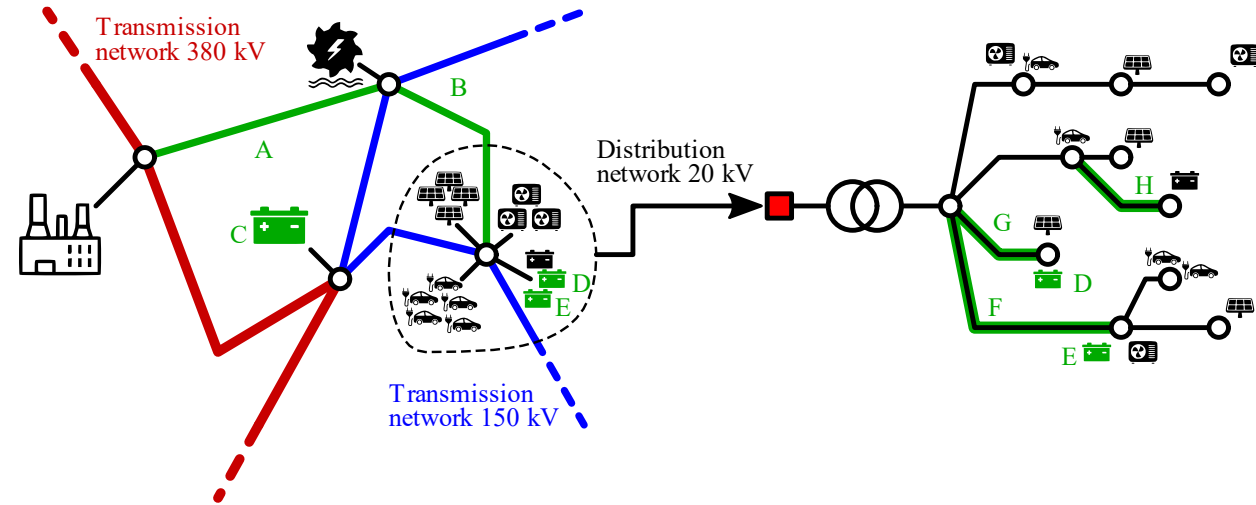
A large portion of the **available flexibility** is expected to be located at **distribution level**, and its exploitation for transmission services needs to consider also lower voltage systems.



Joint Transmission and Distribution Planning

FlexPlan

Optimal planning (for the entire system) needs the simultaneous consideration of both distribution and transmission requirements



Unbearable optimization problem for state-of-the-art of mathematical solvers

- Model complexity (DC+AC OPF)
- Dimension of the problem (number of variables and long-time horizons)



Lack of transparency and standards to exchange information among transmission and distribution system operators

Decomposition of the joint transmission and distribution planning

The Italian case

Transmission network

The Italian regional case consists of a (simplified) transmission network which counts:

- 4160 AC buses
- 5165 AC lines
- 303 transformers
- 20 DC buses
- 26 DC lines (borders excluded)
- 2046 primary substations

(Synthetized) **distribution system**

- 3890 HV/MV transformers
- 774,739 AC buses and 774,738 AC lines

Sections of distribution network subject to overloading and/or voltage issues

- 2030 → overloading: 39% voltage issues: 0.10%
- 2040 → overloading: 55% voltage issues: 0.23%
- 2050 → overloading: 72% voltage issues: 2.39%

Reduction to only congested areas/feeders

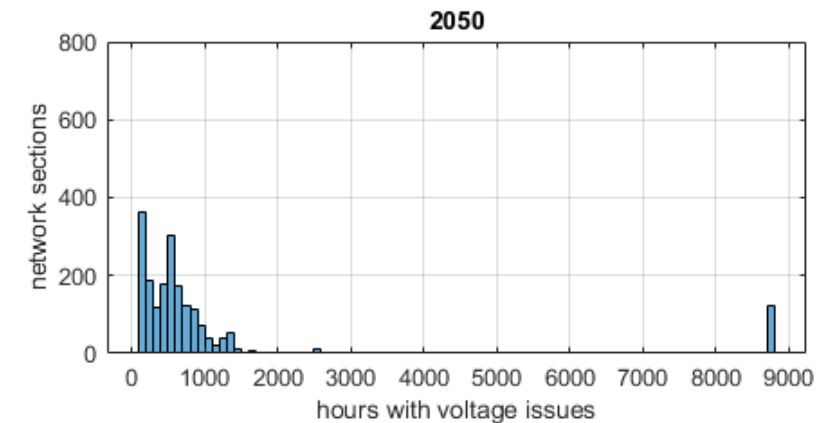
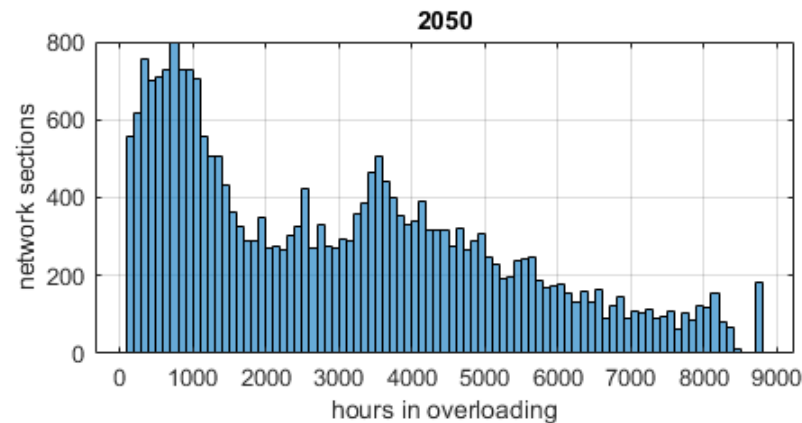
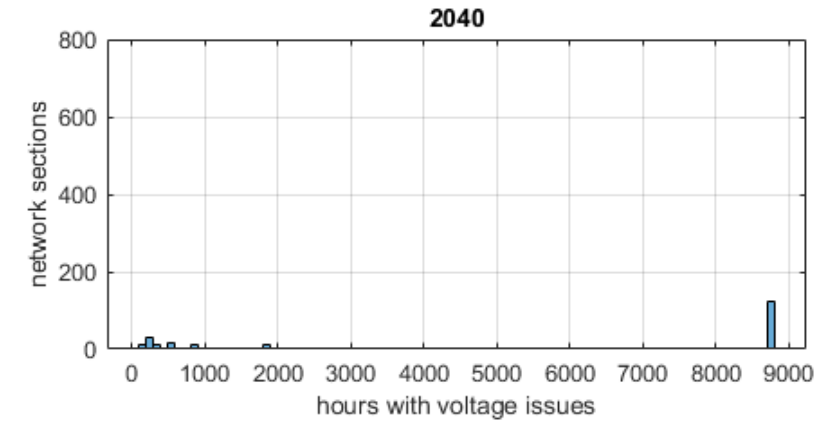
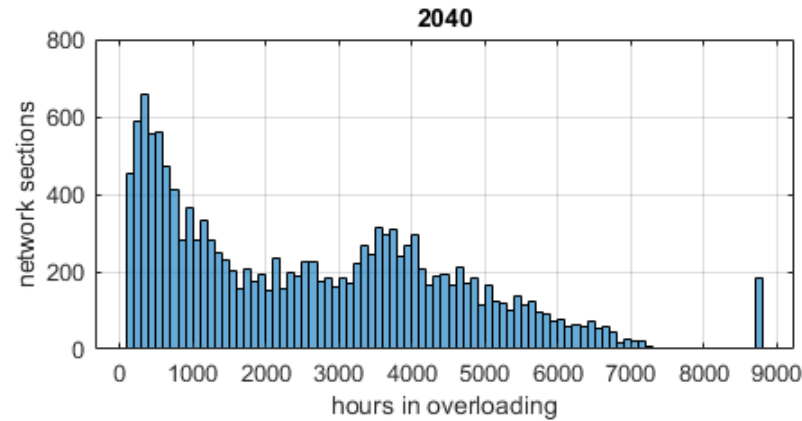
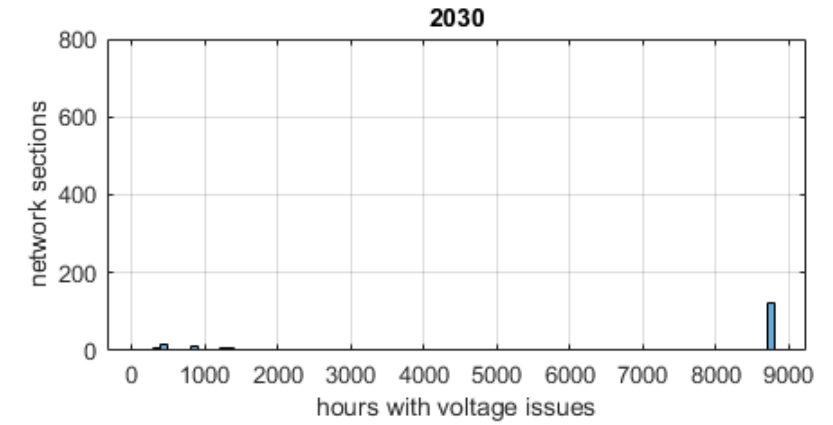
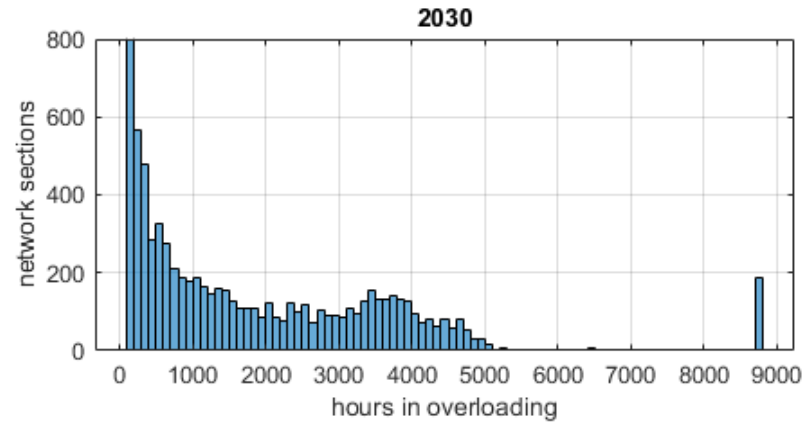
- 744,739 AC buses have been reduced to 68,297 AC buses (reduction to 8.82% of the original size)

The Italian case

Distribution network

Amount of expected congestions and their duration over the synthesized distribution system of Italy.

Thanks to the reduction, each transformer feeds averagely 18 MV nodes (200 before reduction)



Transmission and distribution **separation in planning routines** is still a requirement, but procedures can be updated in order to consider the potential of power/energy flexibility outside of the planning perimeter.

For what concerns **distribution network**, there is a planning conflict

**Minimization of the
distribution planning cost**

min CAPEX+OPEX

such that

- distribution grid constraints are respected

**Maximization of local flexibility
for transmission services**

max flexible power exchange btw. T&D

such that

- distribution grid constraints are respected
- CAPEX and OPEX are disregarded

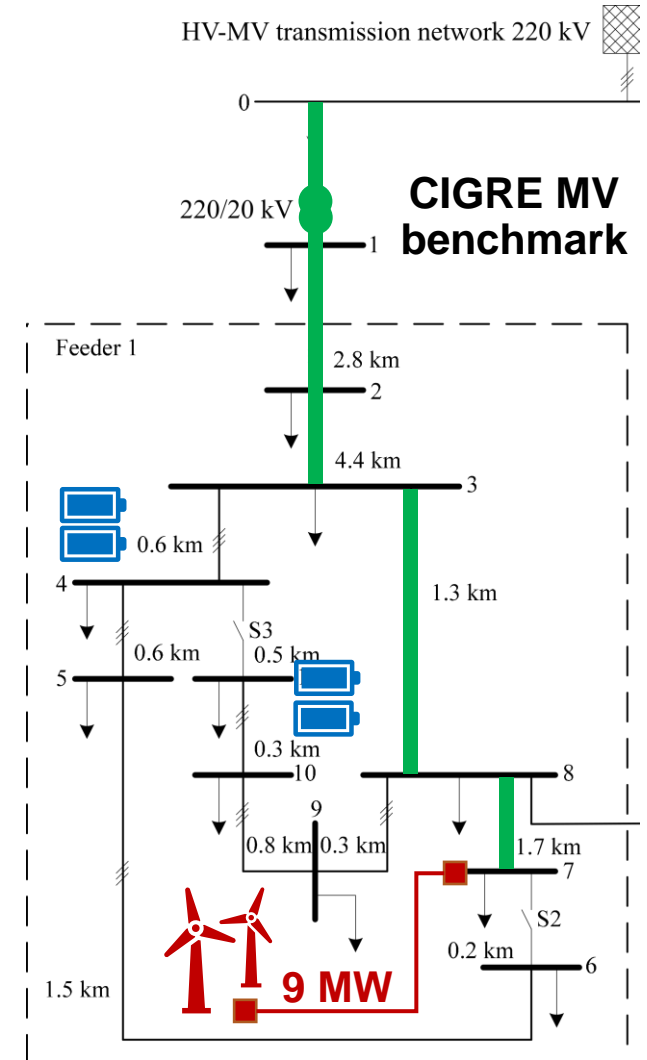
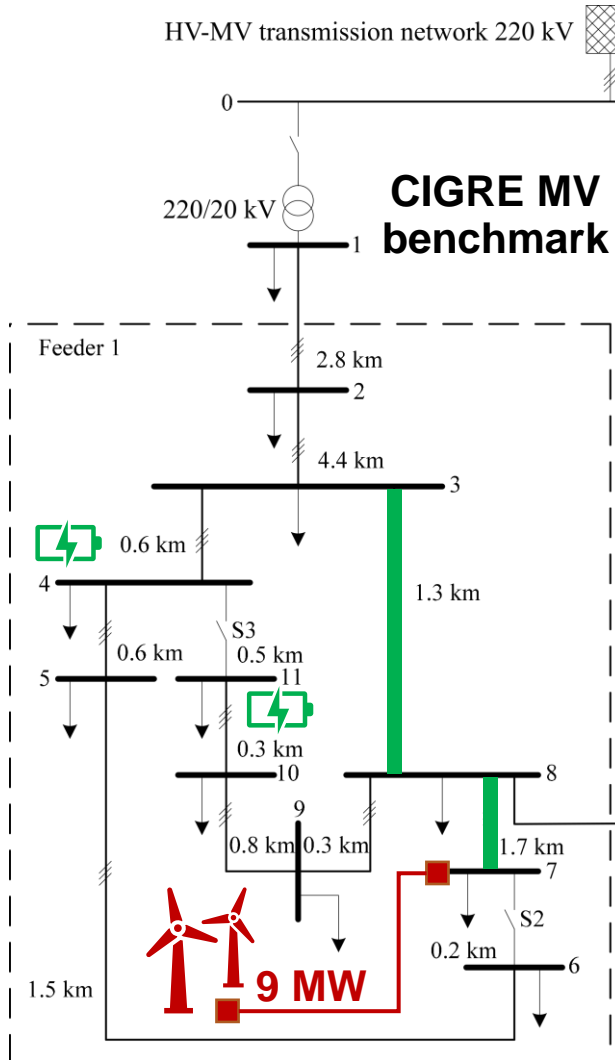
Two distribution planning options

Minimization of the distribution planning cost

- 3 km reinforced lines
- Storage units provide local congestion management services
- CAPEX+OPEX = **691 k€**

Maximization of local flexibility for transmission services

- 10.2 km reinforced lines and substituted distribution transformer
- Local storage units **enhanced** and available for transmission services
- CAPEX = **2,792 k€** (OPEX=0)



More distribution planning options

More options can be explored in order to determine **trade-offs** between minimum planning costs and maximum flexibility for transmission services

| Investment costs (on local network) [k€] | Operation costs (distribution services) [k€] | Equivalent storage flexibility for transmission services |
|--|--|--|
| ✓ 446 | 245 | 1.0 MW / 2.0 MWh |
| ✓ 1,006 | 245 | 2.0 MW / 4.0 MWh |
| ✗ 1,566 | 245 | 2.0 MW / 4.0 MWh |
| ✗ 1,706 | 245 | 2.0 MW / 4.0 MWh |
| ✓ 2,792 | 0 | 3.6 MW / 7.2 MWh |

max **flexible power**
exchange btw. T&D

such that

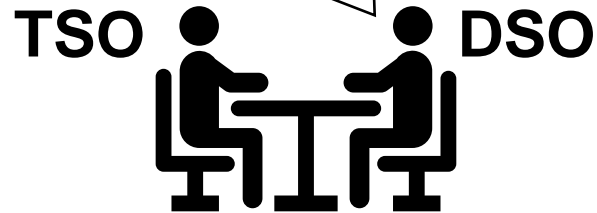
- distribution grid constraints are respected
- CAPEX is limited

intermediate options

Collaborative planning of transmission and distribution network

FlexPlan

| Investment costs (on distrib. network) [k€] | Equivalent storage flexibility for transmission services |
|---|--|
| 446 | 1.0 MW / 2.0 MWh |
| 1,006 | 2.0 MW / 4.0 MWh |
| 2,792 | 3.6 MW / 7.2 MWh |



Simple and efficient cooperation between system operators:

- The identified distribution planning options can be negotiated with a limited exchange of standard and non-sensitive information

Distribution network can be seen as an equivalent storage unit which can be exploited for services addressed to transmission system planning/operation.

The procedure can be repeated for any typology of flexibility resource (demand response, generation curtailment, etc.)

Collaborative planning of transmission and distribution network

Collaborative T&D Planning

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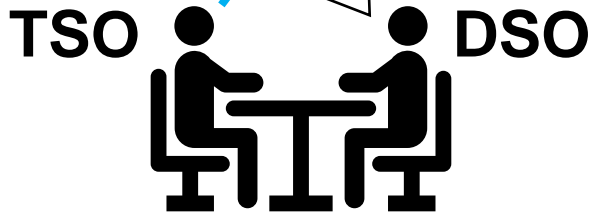
| Investment costs (on distrib. network) [k€] | Equivalent storage flexibility for transmission services |
|---|--|
| 446 | 1.0 MW / 2.0 MWh |
| 1,006 | 2.0 MW / 4.0 MWh |
| 2,792 | 3.6 MW / 7.2 MWh |

Transmission system operator can run its own planning routines (separately) by considering the proposed options and related costs.

min **CAPEX+OPEX**

such that

- transmission grid constraints are respected
- distribution grid planning options are considered



Conclusion

The procedure is currently under validation tests, is characterized by a non-negligible **complexity** and introduces **approximations**.

However, it offers **significant advantages** for a **global optimization** of distribution and transmission systems. It guarantees a **separated** (decoupled) **management** of the transmission and distribution planning problem

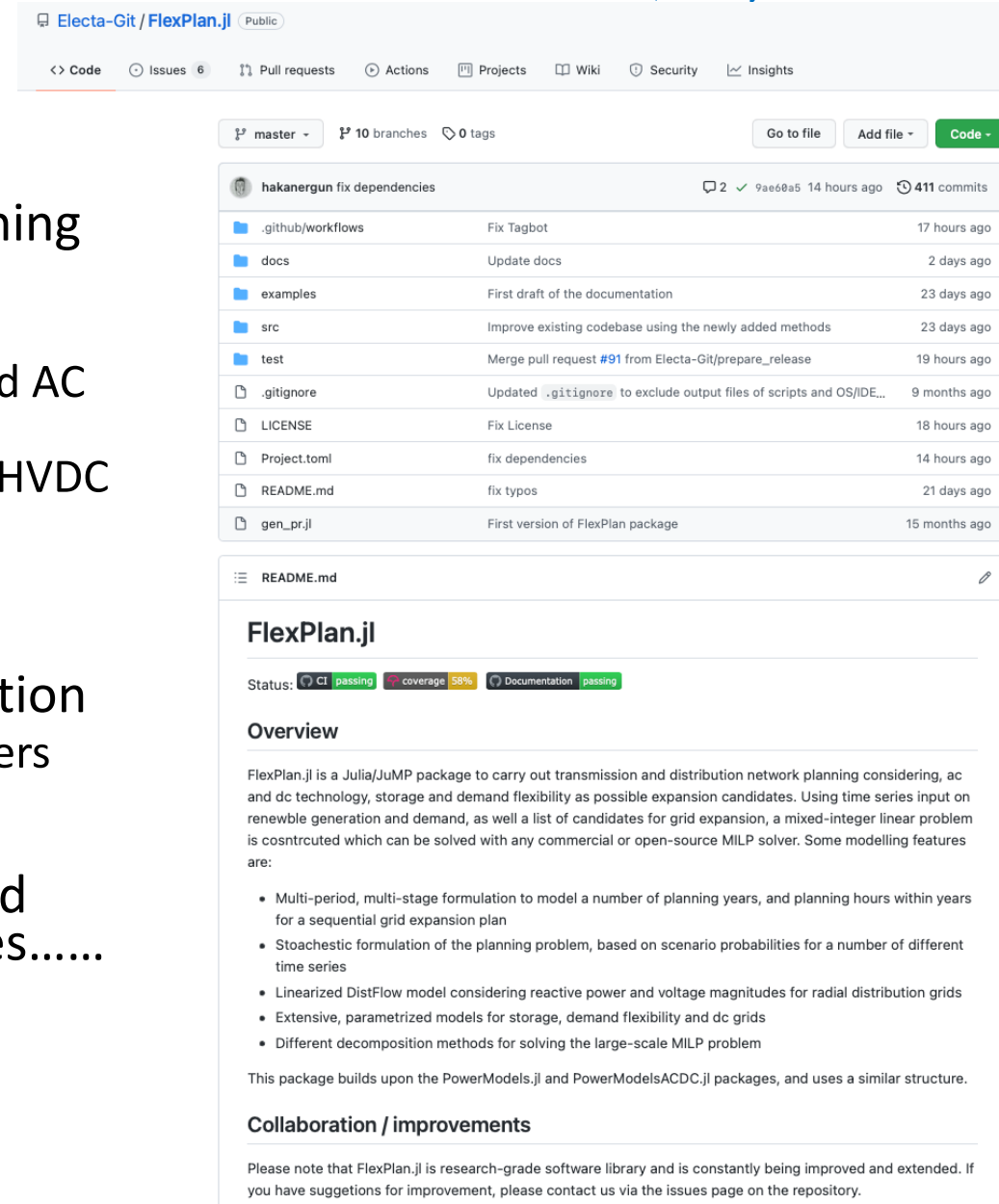
- Potential of distributed flexible resources maximally exploited
 - Not only local services, but lower voltage levels flexibility supports transmission network planning too
- Reduced computational burden
 - Possible solutions for distribution planning are managed separately from the transmission problem
- Simple and efficient **cooperation between system operators**
 - Procedure in line with EU directive 2019/944

Summary

- A variety of different decompositions have been implemented and tested on proof-of-concept test cases
- The performance of the decomposition methods depend strongly on the analysed test cases
- Correct tuning of the optimization solvers are essential for single-shot or decomposed solution
- Temporal decomposition of the planning model, e.g., division in months / weeks as well as T&D network decomposition are inevitable for solving the problem for realistic networks

FlexPlan.jl released!

- Open-source Julia/JuMP implementation of the planning model, including:
 - A variety of different problem types
 - Two distinct network formulations for meshed AC/DC and AC radial distribution grids
 - Parametrised models for demand flexibility, storage and HVDC connections
 - Different model decompositions
- Serves as a testbed for the planning tool implementation
 - Easy to extend, easy to use a variety of optimisation solvers
- Current version v0.1.1, further improvements planned w.r.t. to tool documentation, problem types, examples.....
- More information under: <https://github.com/Electa-Git/FlexPlan.jl>



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master 10 branches 0 tags Go to file Add file Code

| File | Commit | Time ago |
|-------------------|---|---------------|
| .github/workflows | Fix Tagbot | 17 hours ago |
| docs | Update docs | 2 days ago |
| examples | First draft of the documentation | 23 days ago |
| src | Improve existing codebase using the newly added methods | 23 days ago |
| test | Merge pull request #91 from Electa-Git/prepare_release | 19 hours ago |
| .gitignore | Updated .gitignore to exclude output files of scripts and OS/IDE... | 9 months ago |
| LICENSE | Fix License | 18 hours ago |
| Project.toml | fix dependencies | 14 hours ago |
| README.md | fix typos | 21 days ago |
| gen_pr.jl | First version of FlexPlan package | 15 months ago |

README.md

FlexPlan.jl

Status: CI passing coverage 58% Documentation passing

Overview

FlexPlan.jl is a Julia/JuMP package to carry out transmission and distribution network planning considering, ac and dc technology, storage and demand flexibility as possible expansion candidates. Using time series input on renewable generation and demand, as well as a list of candidates for grid expansion, a mixed-integer linear problem is constructed which can be solved with any commercial or open-source MILP solver. Some modelling features are:

- Multi-period, multi-stage formulation to model a number of planning years, and planning hours within years for a sequential grid expansion plan
- Stochastic formulation of the planning problem, based on scenario probabilities for a number of different time series
- Linearized DistFlow model considering reactive power and voltage magnitudes for radial distribution grids
- Extensive, parametrized models for storage, demand flexibility and dc grids
- Different decomposition methods for solving the large-scale MILP problem

This package builds upon the PowerModels.jl and PowerModelsACDC.jl packages, and uses a similar structure.

Collaboration / improvements

Please note that FlexPlan.jl is research-grade software library and is constantly being improved and extended. If you have suggestions for improvement, please contact us via the issues page on the repository.

Thank you...

Hakan Ergun
Matteo Rossini
Marco Rossi

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